

## Appendix B

(not for publication, available at [http://www.severinov.com/AppendixB\\_mechanisms.pdf](http://www.severinov.com/AppendixB_mechanisms.pdf))

### Part 1. Relaxing the assumption $p_{i,j}(\theta_i, \theta_j) > 0$ for any $\theta_i \in \Theta_i, \theta_j \in \Theta_j, i$ and $j$ .

If this assumption does not hold, we proceed as follows. First, introduce the following definition.

**Definition 5**  $T \equiv \{T^1, \dots, T^q\}$  is the finest partition of the set  $\{\theta \in \Theta | p(\theta) > 0\}$ , i.e. the set of type profiles occurring with a positive probability, which satisfies the following property **FP**: For all  $i$  and  $\theta_i \in \Theta_i$ , there exists  $l \in \{1, \dots, q\}$  s.t.  $\{(\theta_i, \theta_{-i}) | \theta_{-i} \in \Theta_{-i}, p(\theta_i, \theta_{-i}) > 0\} \subset T^l$ .

$T$  is well-defined because the trivial partition  $\tilde{T}$  s.t.  $q = 1$  and  $\tilde{T}^1 = \{\theta \in \Theta | p(\theta) > 0\}$  satisfies property **FP**, and a meet of two partitions  $T'$  and  $T''$  possessing property **FP** is also a partition satisfying this property. In fact, if for any pair of types  $\theta_i$  and  $\theta_j$  of any two agents  $i$  and  $j$ , there exists  $\theta_{-i-j} \in \Theta_{-i-j}$  s.t.  $p(\theta_{-i-j}, \theta_i, \theta_j) > 0$ , then  $T$  is trivial, i.e.  $q = 1$ .

Also, note that since  $p_i(\theta_i) > 0$  for all  $i$  and  $\theta_i \in \Theta_i$ , the projection of partition  $T$  on type space  $\Theta_i$  is a partition of  $\Theta_i$  which we denote by  $\{T_i^1, \dots, T_i^q\}$ .

**Definition 6** The decision rule  $x(\theta)$  is ex-ante socially rational for prior  $p(\cdot)$  (*EASR*( $p$ )) if

$$\sum_{\theta \in T^l} \sum_{i=1}^n u_i(x(\theta), \theta) p(\theta) \geq 0 \quad \text{for all } l \in \{1, \dots, q\} \quad (54)$$

Then it is easy to establish the following result:

**Lemma 4** If the allocation profile  $(x(\theta), t(\theta))$  is incentive compatible and interim individually rational, then  $x(\theta)$  is *EASR*( $p$ ), i.e. ex ante socially rational for prior  $p(\cdot)$ .

**Proof** Consider any agent  $i$  and  $\theta_i$  s.t.  $\theta_i \in T_i^l$  for some  $l \in \{1, \dots, q\}$ , i.e.  $(\theta_i, \theta_{-i}) \in T^l$  if  $p(\theta_i, \theta_{-i}) > 0$ . By Property **FP**, *IR*( $\theta_i$ ) is equivalent to the following:

$$\sum_{\theta_{-i}: (\theta_i, \theta_{-i}) \in T^l} (u_i(x(\theta_{-i}, \theta_i), (\theta_{-i}, \theta_i)) + t_i(\theta_{-i}, \theta_i)) p(\theta_{-i}, \theta_i) \geq 0 \quad (55)$$

Summing (55) over all  $\theta_i \in T_i^l$  and then adding the resulting inequalities together for all  $i \in \{1, \dots, n\}$ , we obtain  $\sum_{\theta \in T^l} \sum_{i \in \{1, \dots, n\}} (u_i(x(\theta), \theta) + t_i(\theta)) p(\theta) \geq 0$ . Budget-balancing then implies (54). ■

Careful reading of the proofs confirms that in this case Theorem 1 holds for any  $EASR(p)$  decision rule. This property is required to establish modified Lemma A3 in the proof. Furthermore, Theorem 1 holds with the following modification: the expected social surplus conditional on a particular element of the partition  $T$  can be allocated in an arbitrary way to the agent-types within this element of the partition.